

Programmable Actuator Catalog

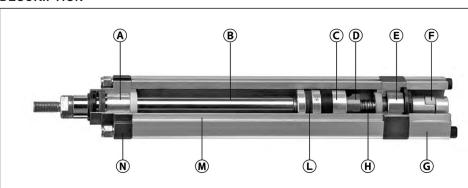




ECL3 ELECTRIC CYLINDERS NORMAL DUTY SERIES 10

ISO 15552

DESCRIPTION



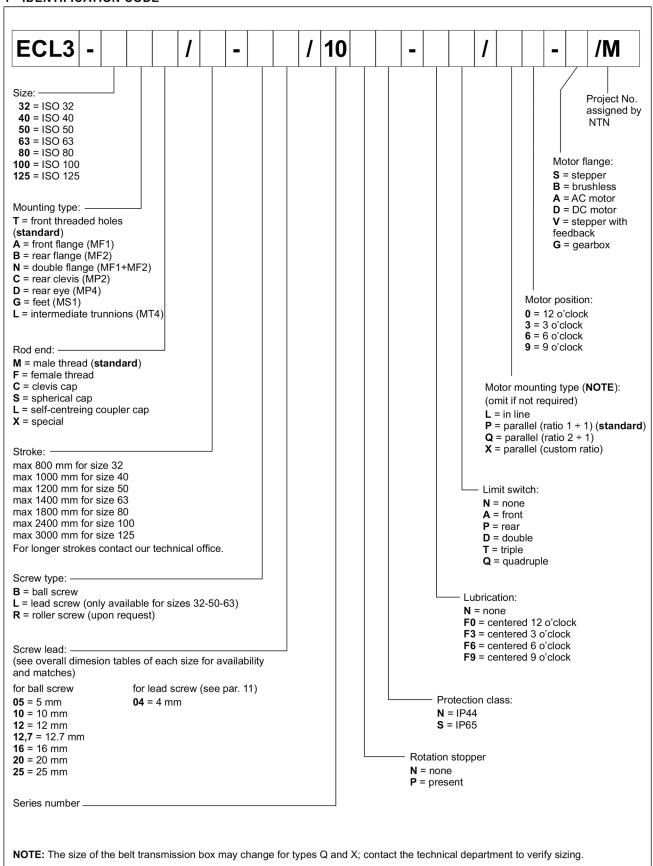
- A Rod guide
- B Rod
- C Piston
- D Nut
- E Bearing
- F Coupling
- G Coupling carter
- H Screw
- L Magnetic ring
- u Magne M - Barrel
- N Front cap

- Electric cylinder made with mounting interfaces in compliance with ISO 15552.
- The linear motion transmission is obtained by precise and high-efficiency ball-screw system, with hardened shaft and nut.
- All ball screws have high load ratings, thus guaranteeing endurance even in demanding applications. The cylinder design is realized to minimize vibrations: the piston is precisely driven into the barrel with zero backlash sliding rings; the screw-shaft end is supported by strong bushing; the rod is driven into the front-cap by a long linear guide. The cylinder can be equipped with robust integrated anti-rotation device.
- The piston is equipped with magnetic ring and the barrel has external slots to accommodate possible sensors. The rod has increased external diameter and thickness in order to have maximum stiffness and high resistance to radial and buckling loads. The screw is supported with high trust bearings to allow high load transmission in both directions.
- High force timing belt is provided for parallel motor mounting, to guarantee robustness of torque transmission.
- Many pneumatic accessories can be used for the electric cylinder attachment and mounting, intermediate trunnions included.

PERFORMANCES

Size		32	40	50	63	80	100	125
Maximum axial force	N	2100	3400	6400	9500	12700	53500	88300
Maximum speed	mm/s	1111	1333	1422	1333	1333	702	533
Maximum acceleration	m/s²	6	8	10	13	16	13	13
Standard stroke up to	mm	800	1000	1200	1400	1800	2400	3000
Maximum average axial force for 2500 km life	N	832	1375	2277	2453	3635	12442	19744
Ambient temperature range	°C	-20 / +100						
Max air humidity allowed for IP65 (without condensation)	%	90						
Protection degree			IP44 or IP65					

1 - IDENTIFICATION CODE



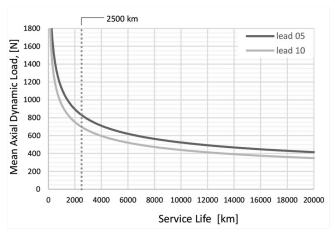
4 - ECL3-32

4.1 - Technical Characteristics

MECHANICAL	Rod diameter	mm	2	20
MECHANICAL	Rod end		M10x1.25	
	Nominal diameter	mm	12	12
BALL SCREW	Lead	mm	5	10
	Dynamic load	N	6600	4400
	Max force - in line	N	2100	2100
	Max torque - in line	Nm	2.0	3.9
FORCE	Max force - parallel	N	2100	2100
	Max torque - parallel	Nm	2.0	3.9
	Dynamic axial force at 2500 km lifetime	N	832	698
SPEED	Max speed	rpm	6667	6667
SPEED	iwax speed	mm/s	556	1111
ACCELERATION	Max acceleration	m/s²	3.2	6.4
EFFICIENCY	In line	%	86	88
EFFICIENCY	Parallel	%	77	79

4.2 - Service Life

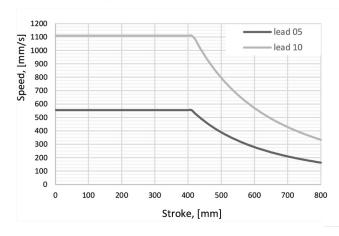
The service life depends on average dynamic axial load.

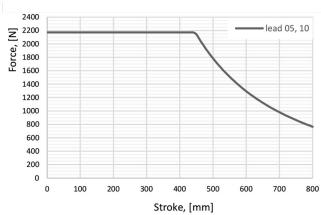


NOTES

- Nominal life is a statistical value and refers to 90% reliability
- Correct working conditions: i.e. no lateral-load, no over-load, right lubrication, no over-temperature, no shortstroke application.

4.3 - Permissible Speed





2 - COMMON TECHNICAL CHARACTERISTICS

ACCURACY		mm	± 0.035
	Ambient temperature range	°C	-20 / +100 (cylinder without motor)
ENVIRONMENT	Protection class		IP44 or IP65
	Humidity	%	0 ÷ 90
	Reference standard		ISO 15552
	Duty cycle	%	100
	Internal antirotation		available on all sizes
MECHANICAL	Rod end		male or female
	Rod material		chromium-plated (standard) stainelss steel upon request
	Mounting		on front cap or with accessories
	End stroke sensor		available on all sizes

3 - FEATURES OF USE

3.1 - Field of Application

- In any generic system for automation applications;
- Replacing of pneumatic cylinders where accurate speed profile control is required. The electric cylinder works with constant and controlled acceleration/deceleration ramps, even with variable load.
- When high push/pull force is needed without the use of hydraulics.
- In any motion system where no-pollution or extremely-low noise emission are required.

3.2 - Applications

ISO 15552 ECL3 electric cylinders are the right solution for all those applications that require accurate and controlled positioning. They offer the opportunity to use pre-set solutions to solve the design and commissioning of automation systems quickly and simply.

The installation simplicity and the different construction types make the ECL3 cylinder a reference point in this kind of product.

The wide possibility of choice among different types allows the use of the ECL3 even in demanding and critical applications, as they offer force capabilities and dynamic load ratings decisively heavier than standard market proposals.

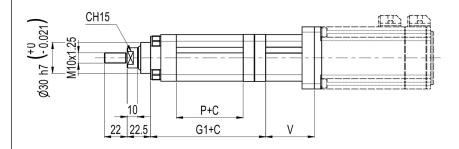
The possibility to use most of standard pneumatic ISO 15552 accessories for the same size is an additional practical and cost advantage in mounting the cylinders.

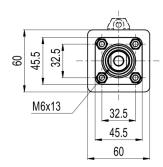


dimensions in mm

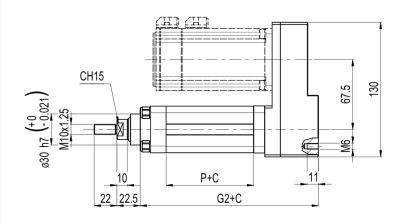
4.5 - ECL3-32 Overall Mounting Dimensions

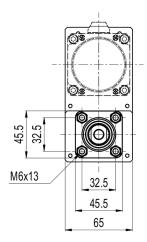
In-line motor mounting





Parallel motor mounting





Ball Screw	Р	G1	G2
12X05	73.5	120.4	161.25
12X10	79.5	126.4	167.25

Lead Screw	Р	G1	G2
14X04	64.5	111.4	152.25

C = Stroke value

 \mathbf{V} = Depending on motor dimensions

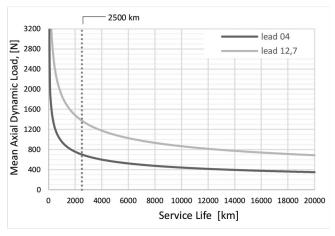
5 - ECL3-40

5.1 - Technical Characteristics

MECHANICAL	Rod diameter	mm	:	25
MECHANICAL	Rod end		M12x1.25	
	Nominal diameter	mm	14	12.7
BALL SCREW	Lead	mm	4	12.7
	Dynamic load	N	6000	8000
	Max force - in line	N	3000	2400
	Max torque - in line	Nm	2.3	5.5
FORCE	Max force - parallel	N	3000	3400
	Max torque - parallel	Nm	2.3	7.9
	Dynamic axial force at 2500 km lifetime	N	702	1375
SPEED	Max speed	rpm	5714	6299
SPEED	iwax speed	mm/s	381	1333
ACCELERATION	Max acceleration	m/s²	2.5	8.1
EFFICIENCY	In line	%	84	88
EFFICIENCY	Parallel	%	76	80

5.2 - Service Life

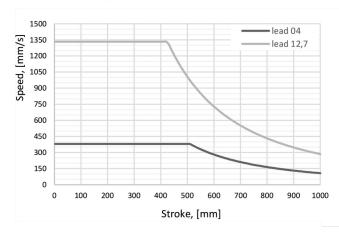
The service life depends on average dynamic axial load.

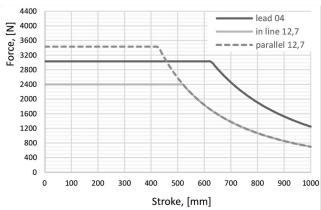


NOTES

- Nominal life is a statistical value and refers to 90% reliability.
- Correct working conditions: i.e. no lateral-load, no over-load, right lubrication, no over-temperature, no shortstroke application.

5.3 - Permissible Speed

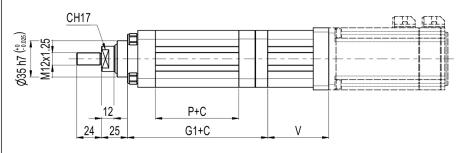


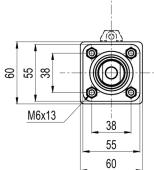


dimensions in mm

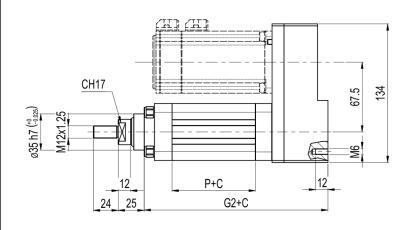
5.5 - ECL3-40 Overall Mounting Dimensions

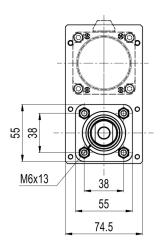
In-line motor mounting





Parallel motor mounting





Ball Screw	Р	G1	G2
12.7X12.7	80.5	135.64	177.6
14X04	64.5	119.6	161.1

C = Stroke value

V = Depending on motor dimensions

ECL3

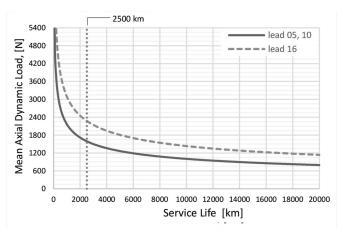
6 - ECL3-50

6.1 - Technical Characteristics

MECHANICAL	Rod diameter	mm		25	
WECHANICAL	Rod end		M16x1.5		
	Nominal diameter	mm	15	15	15
BALL SCREW	Lead	mm	5	10	16
	Dynamic load	N	12655	9908	12263
	Max force - in line	N	6300	3200	2050
	Max torque - in line	Nm	5.9	5.9	5.9
FORCE	Max force - parallel	N	6400	5400	6400
	Max torque - parallel	Nm	6.0	9.9	18.5
	Dynamic axial force at 2500 km lifetime	N	1594	1573	2276
SPEED	May anad	rpm	5333	5333	5333
SPEED	Max speed	mm/s	444	889	1422
ACCELERATION	Max acceleration	m/s²	3.2	6.4	10.2
	In line	%	85	88	88
EFFICIENCY	Parallel	%	77	79	80

6.2 - Service Life

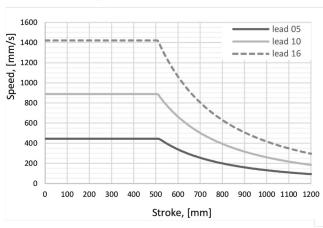
The service life depends on average dynamic axial load.

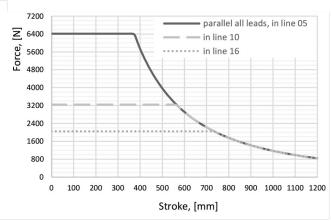


NOTES

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- Correct working conditions: i.e. no lateral-load, no over-load, right lubrication, no over-temperature, no shortstroke application.

6.3 - Permissible Speed

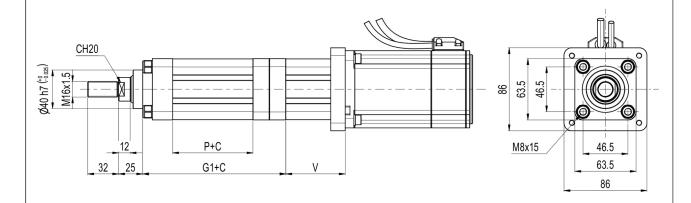




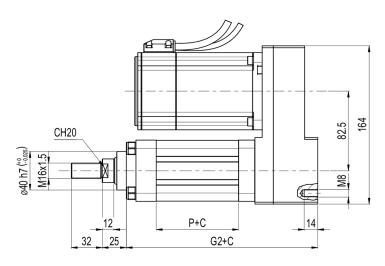
dimensions in mm

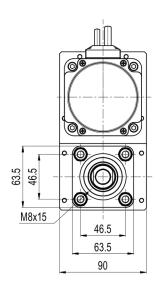
6.5 - ECL3-50 Overall Mounting Dimensions

In-line motor mounting



Parallel motor mounting





Ball Screw	Р	G1	G2
16X05	83.2	148.3	196.3
16X10	83.2	148.3	196.3
16X16	85.2	150.3	198.3

L	ead Screw	Р	G1	G2
	16X04	75.5	140.6	188.6

C = Stroke value

V = Depending on motor dimensions

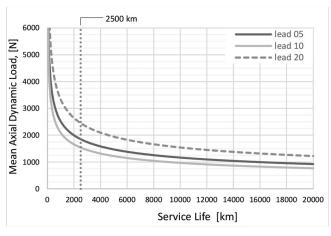
7 - ECL3-63

7.1 - Technical Characteristics

MECHANICAL	Rod diameter	mm		30	
WECHANICAL	Rod end		M16x1.5		
	Nominal diameter	mm	20	20	20
BALL SCREW	Lead	mm	5	10	20
	Dynamic load	N	14715	9712	12262
	Max force - in line	N	9500	7300	7300
	Max torque - in line	Nm	9.1	13.6	26.5
FORCE	Max force - parallel	N	9500	7300	7300
	Max torque - parallel	Nm	9.1	13.6	26.5
	Dynamic axial force at 2500 km lifetime	N	1854	1542	2453
SPEED	Max speed	rpm	4000	4000	4000
SPEED	iwax speed	mm/s	333	667	1333
ACCELERATION	Max acceleration	m/s²	3.2	6.4	12.7
EFFICIENCY	In line	%	84	87	88
EFFICIENCY	Parallel	%	75	78	80

7.2 - Service Life

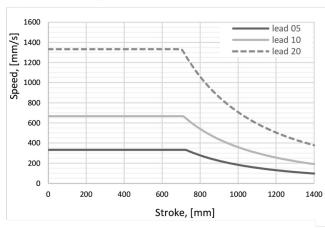
The service life depends on average dynamic axial load.

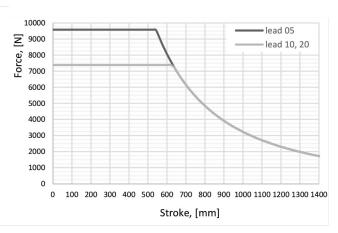


NOTES

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- Correct working conditions: i.e. no lateral-load, no over-load, right lubrication, no over-temperature, no shortstroke application.

7.3 - Permissible Speed

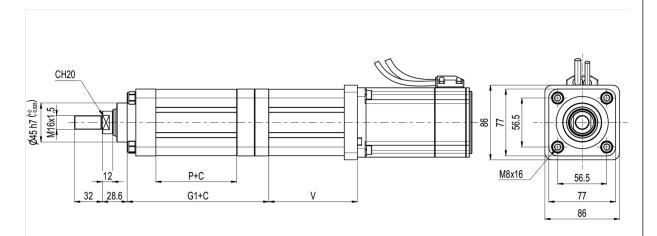




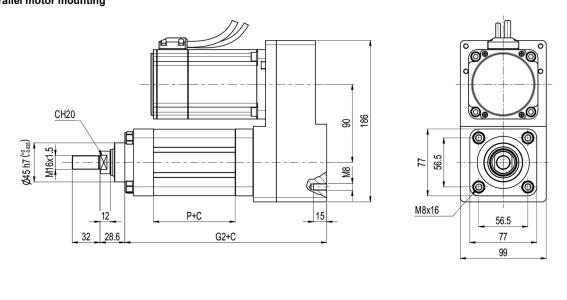
dimensions in mm

7.5 - ECL3-63 Overall Mounting Dimensions

In-line motor mounting



Parallel motor mounting



Ball Screw	P	G1	G2
20X05	93.1	163.1	231.6
20X10	93.1	163.1	231.6
20X20	95.1	165.1	233.6

Lead Screw	Р	G1	G2
20X04	93	163	231.5

C = Stroke value

V = Depending on motor dimensions

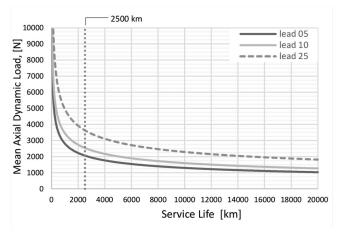
8 - ECL3-80

8.1 - Technical Characteristics

MECHANICAL	Rod diameter	mm		45	
WECHANICAL	Rod end		M20x1.5		
	Nominal diameter	mm	25	25	25
BALL SCREW	Lead	mm	5	10	25
	Dynamic load	N	16383	15990	16873
	Max force - in line	N	12100	11500	9900
	Max torque - in line	Nm	11.7	21.3	45
FORCE	Max force - parallel	N	12100	11500	12700
	Max torque - parallel	Nm	11.7	21.3	57.4
	Dynamic axial force at 2500 km lifetime	N	2064	2538	3635
SPEED	Max speed	rpm	3200	3200	3200
SPEED	wax speed	mm/s	267	533	1333
ACCELERATION	Max acceleration	m/s²	3.2	6.4	15.9
EFFICIENCY	In line	%	82	86	88
EFFICIENCY	Parallel	%	74	77	80

8.2 - Service Life

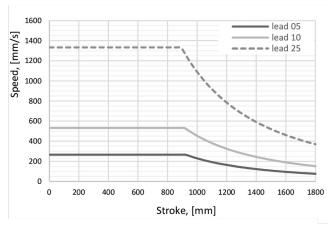
The service life depends on average dynamic axial load.

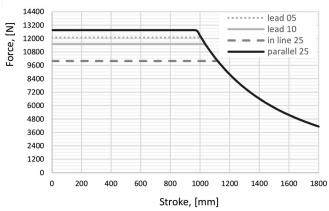


NOTES

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- Correct working conditions: i.e. no lateral-load, no over-load, right lubrication, no over-temperature, no shortstroke application.

8.3 - Permissible Speed





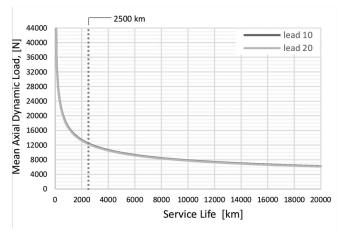
9 - ECL3-100

9.1 - Technical Characteristics

MECHANICAL	Rod diameter	mm	70		
WECHANICAL	Rod end		M42x2		
	Nominal diameter	mm	38	38	
BALL SCREW	Lead	mm	10	20	
	Dynamic load	N	78382	61509	
	Max force - in line	N	53500	53500	
	Max torque - in line	Nm	101.5	196.1	
FORCE	Max force - parallel	N	53500	53500	
	Max torque - parallel	Nm	101.5	196.1	
	Dynamic axial force at 2500 km lifetime	N	12442	12302	
SPEED	Max speed	rpm	2105	2105	
SPEED	Max speed	mm/s	351	702	
ACCELERATION	Max acceleration	m/s²	6.4	12.7	
EFFICIENCY	In line	%	84	87	
EFFICIENCY	Parallel	%	79	82	

9.2 - Service Life

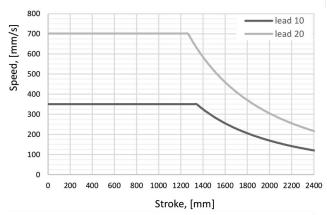
The service life depends on average dynamic axial load.

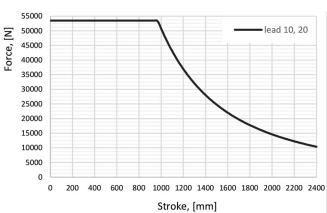


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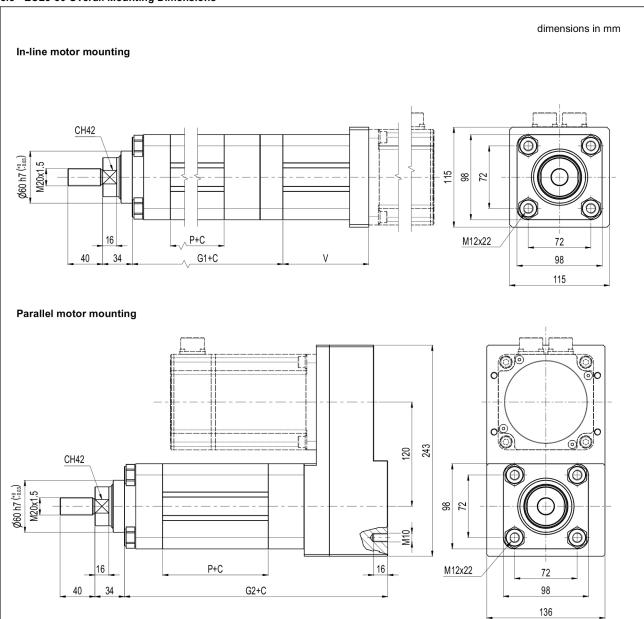
- Nominal life is a statistical value and refers to 90% reliability
- Correct working conditions: i.e. no lateral-load, no over-load, right lubrication, no over-temperature, no shortstroke application.

9.3 - Permissible Speed





8.5 - ECL3-80 Overall Mounting Dimensions



Ball Screw	Ball Screw P		G2	
25X05	121.4	233.2	302.9	
25X10	121.1	233.2	302.9	
25X25	121.1	233.2	302.9	

C = Stroke value

V = Depending on motor dimensions

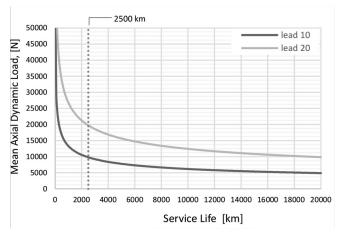
10 - ECL3-125

10.1 - Technical Characteristics

MECHANICAL	Rod diameter	mm	85		
WECHANICAL	Rod end		M48x2		
	Nominal diameter	mm	50	50	
BALL SCREW	Lead	mm	10	20	
	Dynamic load	N	78382	98718	
	Max force - in line	N	63500	88300	
FORCE	Max torque - in line	Nm	123	327.1	
	Max force - parallel	N	63500	88300	
	Max torque - parallel	Nm	123	327.1	
	Dynamic axial force at 2500 km lifetime	N	12442	19744	
SPEED	Max speed	rpm	1600	1600	
SPEED	iviax speed	mm/s	267	533	
ACCELERATION	Max acceleration	m/s²	6.4	12.7	
EFFICIENCY	In line	%	82	86	
EFFICIENCY	Parallel	%	77	81	

10.2 - Service Life

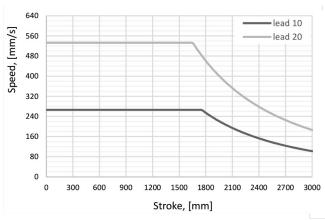
The service life depends on average dynamic axial load.

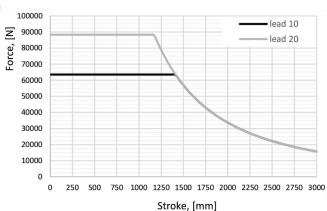


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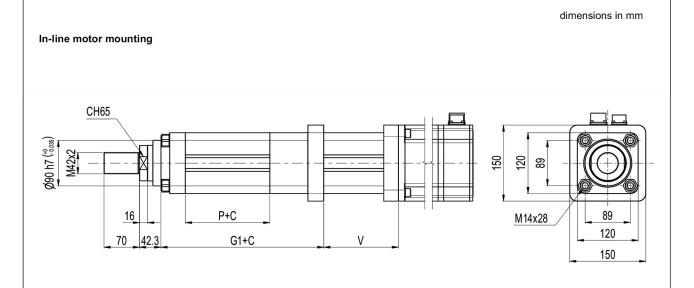
- Nominal life is a statistical value and refers to 90% reliability
- Correct working conditions: i.e. no lateral-load, no over-load, right lubrication, no over-temperature, no shortstroke application.

10.3 - Permissible Speed

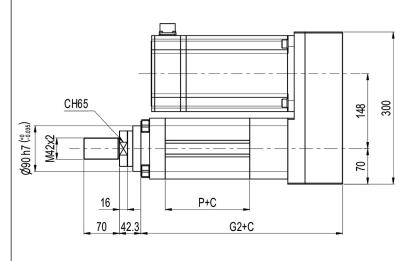


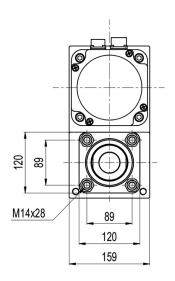


9.5 - ECL3-100 Overall Mounting Dimensions



Parallel motor mounting





Ball Screw	Р	G1	G2	
38X10	166.5	321.1	397.8	
38X20	166.5	321.1	397.8	

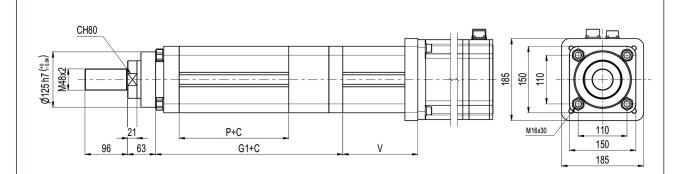
C = Stroke value

V = Depending on motor dimensions

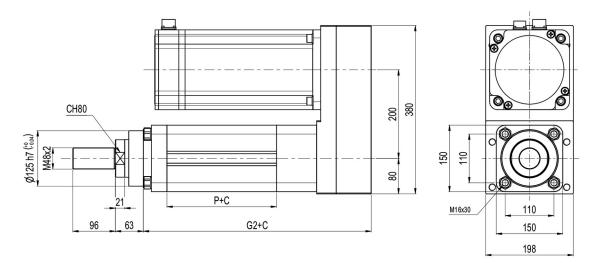
10.5 - ECL3-125 Overall Mounting Dimensions

dimensions in mm

In-line motor mounting



Parallel motor mounting



Ball Screw P		G1	G2	
50X10	222	397.5	489.2	
50X20	247	422.5	514.2	

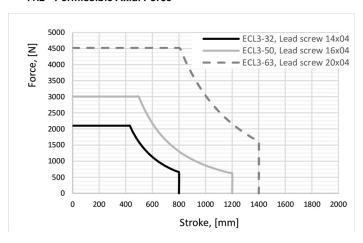
C = Stroke valueV = Depending on motor dimensions

11 - LEAD SCREW TYPES

This screw type is available is available only for actuators in size 32, 50 and 63.

CYLINDER SIZE			32	50	63
MECHANICAL	Rod diameter		20	25	30
MECHANICAL	Rod end		M10x1.25	M16x1.5	M16x1.5
LEAD SCREWS	Nominal diameter	mm	14	16	20
LEAD SCREWS	Lead	mm	4	4	4
FORCE/TOROUE	Max force	N	2104	3008	4520
FORCE/TORQUE	Max torque	Nm	1.6	2.3	3.5
EFFICIENCY	In line	%	41	37	32
LITIOILING	Parallel	%	37	34	29

11.2 - Permissible Axial Force



NOTES: Correct working conditions: i.e. no lateral-load, no over-load, right lubrication, no over-temperature, no short-stroke application.

The permissible force is calculated considering pushing condition with free rod-end and fixed barrel. Contact us for different load applications.

Contact us for any doubt.

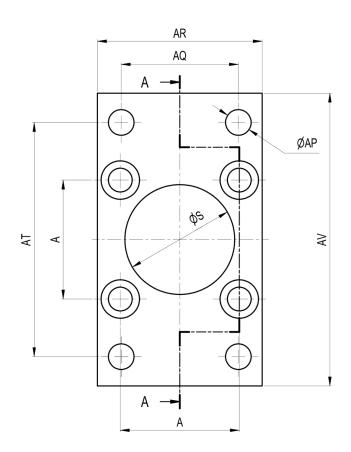


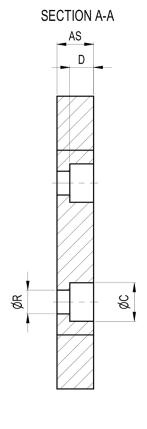
12 - MOUNTING TYPE A AND B



dimensions in mm

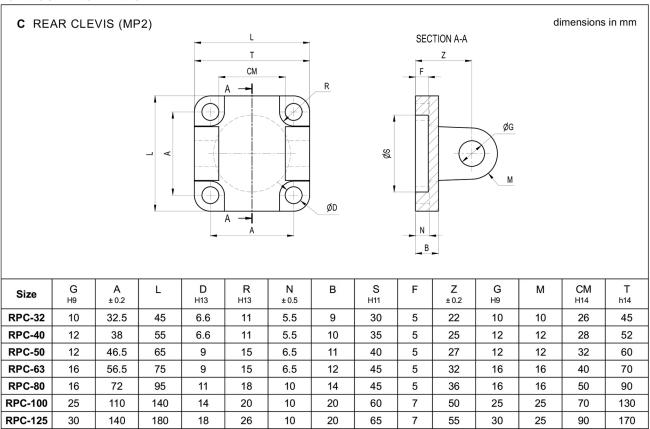
B REAR FLANGE (MF2)



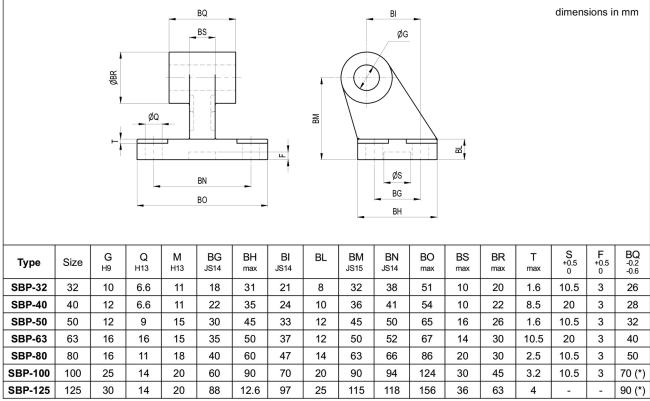


Size	S H11	A ± 0.2	AP H13	R	AS ± 0.2	AR	AQ JS14	AT JS14	AV	С	D
FFP-32	30	32.5	7	6.5	10	45	32	64	80	10.5	6.5
FFP-40	35	38	9	6.5	10	52	36	72	90	10.5	6.5
FFP-50	40	46.5	9	8.5	12	65	45	90	110	13.5	8.5
FFP-63	45	56.5	9	8.5	12	75	50	100	120	13.5	8.5
FFP-80	60	72	12	12.5	18	95	63	126	150	19	13
FFP-100	90	89	14.5	14.5	20	115	75	150	170	22	15
FFP-125	125	110	16.5	16.5	25	140	90	180	205	25	18

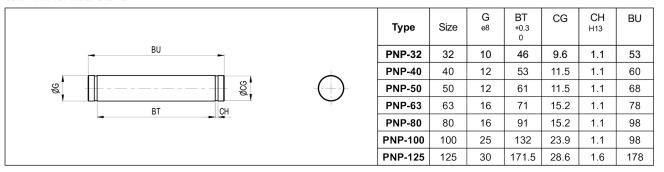
13 - MOUNTING TYPE C

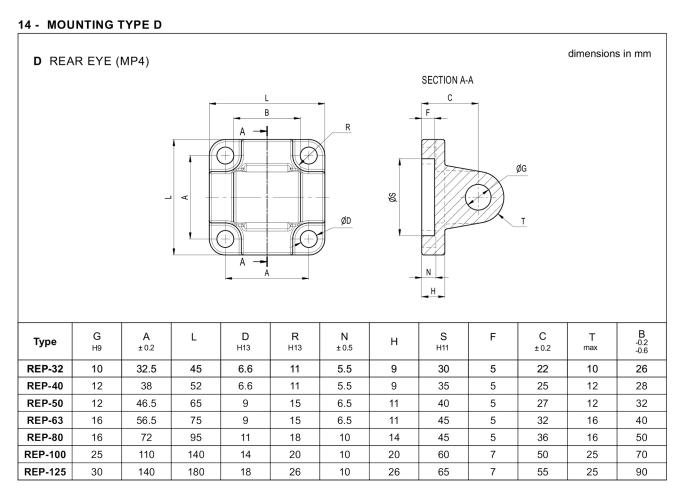


13.1 - Rear Square Bracket

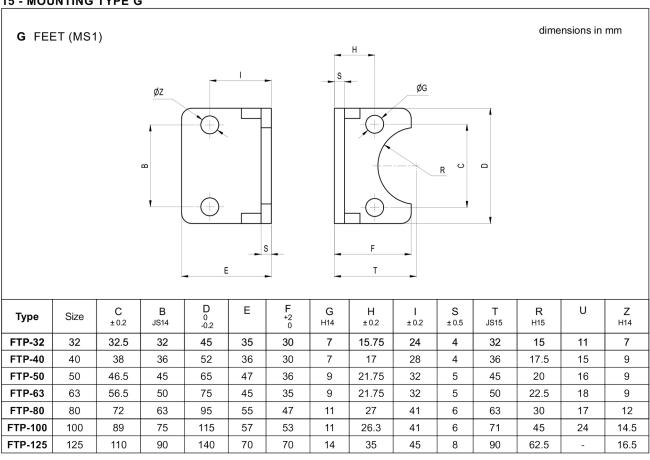


13.2 - Pin for Rear Clevis

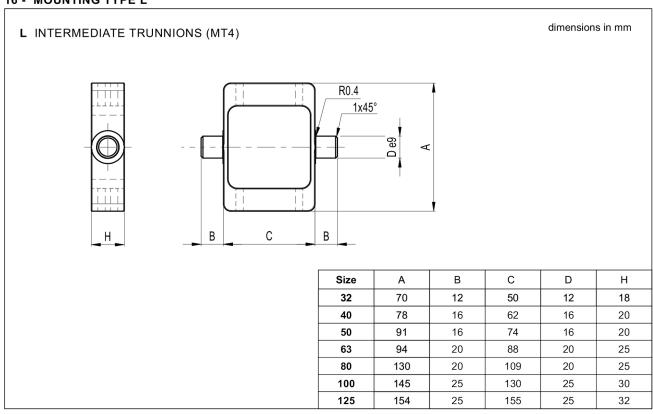




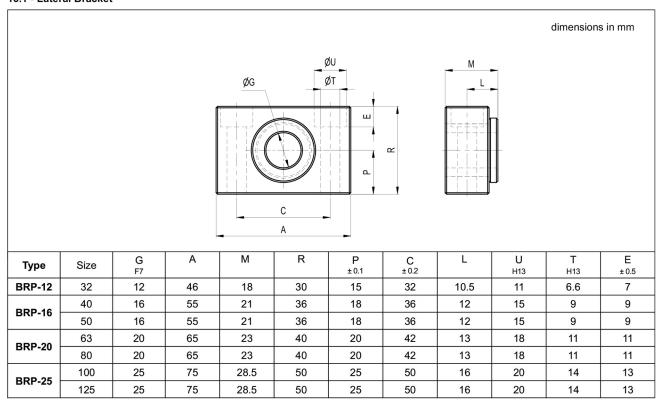
15 - MOUNTING TYPE G



16 - MOUNTING TYPE L

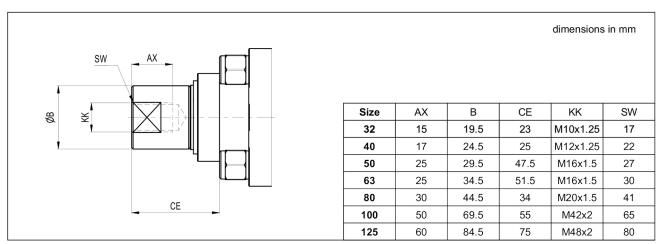


16.1 - Lateral Bracket

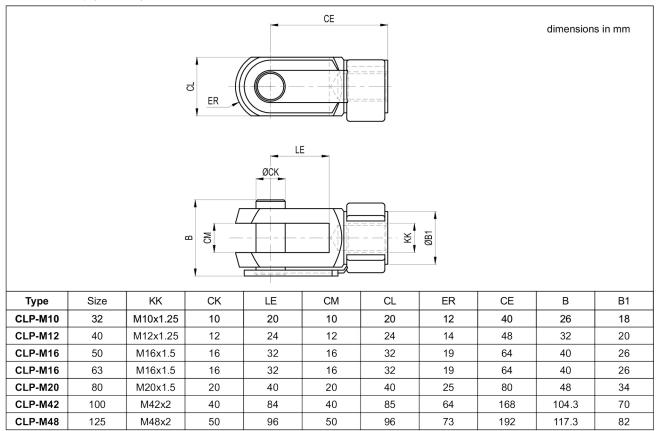


17 - OVERALL MOUNTING DIMENSIONS FOR ROD END

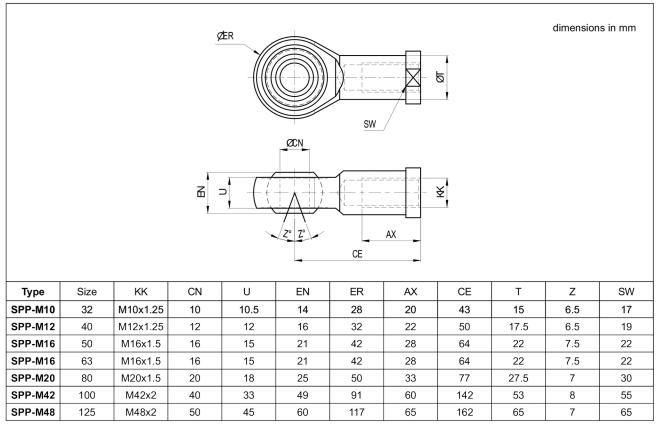
17.1 - Female Thread



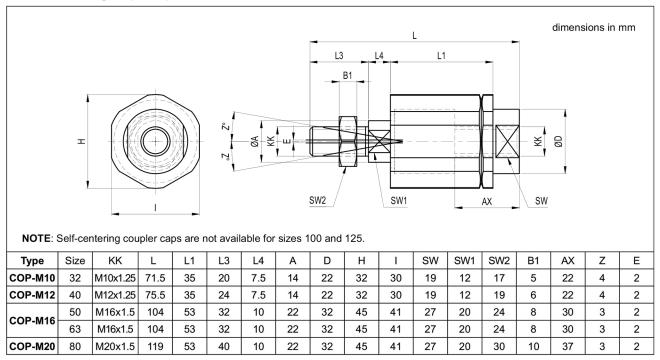
17.2 - Clevis Cap (ISO 8140)



17.3 - Spherical Cap (ISO 8139)



17.4 - Self-Centering Coupler Cap



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